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 $x(0) \sim (\bar{x}_0, P_0)$; and $x(0)$ mutually
uncorrelated. By using Tables 2.1 and
2.2 we can write the covariance update
equations for Equation 3.2 as

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the sampled version of Equation 2.98a,
which we can write as $x_{k+1} = A_s x_k + B_s u_k + w_k$ (2.103) $A_s = e^{AT} T^{-1} s B = e^{A\tau} B \Delta\tau$ (2.104) with (2.105) 0 To find the
covariance Q_s of the new noise

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sequence w_k in terms of Q , write $Q_s =$
 $w_k w_k^T (k+1)^T e^{A[(k+1)^T - \tau]} G w(\tau)$
 $) w(\sigma)^T G^T e^{A^T [(k+1)^T - \sigma]} d\tau d\sigma k^T$

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PART I: OPTIMAL ESTIMATION

This motivates us to consider robust and optimal estimation of the parametric component in semiparametric conditional moment restriction models without nonparametric identification.

Our focus is on robust and optimal estimation, while previous studies focus on robust inference; see Chen et al., 2011a , Chen et al., 2011b , Hong, 2017 , Tao, 2014 and Chernozhukov et al. (2015) .

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